

[22] CT-FEM ASM (Stress analysis of asymmetry gears)

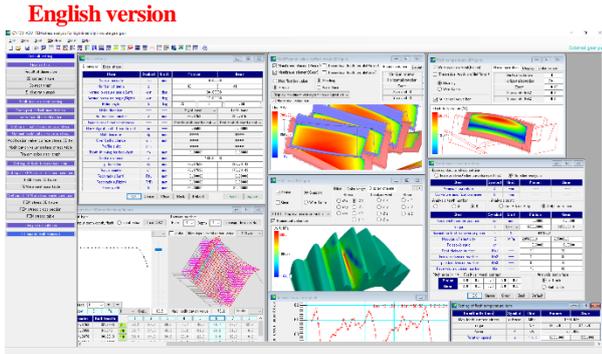


Fig.22.1 CT-FEM ASM

22.1 Abstract

Asymmetric gears can increase tooth loading capacity without changing gear size or material. Compared to standard pressure angle, Hertz stress decreases, friction coefficient and sliding ratio are small. Therefore, the flash temperature is low. For details, please refer to [Appendix H].

CT-FEM ASM is FEM stress analysis software for asymmetric tooth gear. Like CT-FEM Opera iii, it can calculate flash temperature, friction coefficient, oil film thickness, occurrence probability and lifetime of scuffing and wear, and addition of tooth edge contact analysis and optimal tooth surface modification function. Fig.22.1 shows the whole screen.

22.2 Software structure

The structure of CT-FEM ASM is shown in Table 22.1. ○ in the table is included in the basic software, and ⊙ is optional. Applicable gear: involute spur and helical gear (external gear, internal gear)

Table 22.1 software structure

Item	Structure
<1> Basic rack (asymmetry tooth profile)	○
<2> Gear dimension	○
<3> Meshing drawing	○
<4> Tooth modification	○
<5> Tooth surface stress distribution (3D)	○
<6> Tooth surface evaluation ⁽¹⁾ friction coefficient, oil film thickness, calorific potential, Power loss, PV, PVT	○
<7> Scuffing probability of occurrence ⁽¹⁾	○
<8> Wear probability of occurrence ⁽¹⁾	○
<9> Life time ⁽¹⁾	○
<10> Power loss ⁽¹⁾	○
<11> 3D-FEM	○
<12> Edge contact analysis	⊙
<13> Transmission analysis, Fourier analyses, CSV	⊙
<14> Internal gear	⊙
<15> Best tooth surface modification	⊙

(1) Doesn't support a plastic gear

22.3 Property (Basic rack)

A setting screen is shown to Fig.22.3.

- Gear combination : external × external, external × internal
- Basic rack : standard, low, special
- tooth tip circle decision : normal, equal clearance

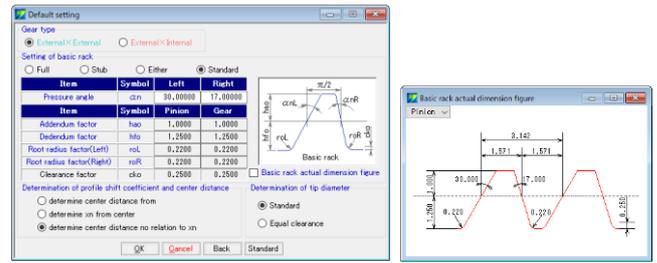


Fig.22.2 property (basic rack)

22.4 Gear dimensions

Gear dimension calculates parts dimensions, contact ratio, sliding ratio, tooth thickness and so on. The gear with undercut determines the contact rate based on the TIF (True Involute Form) diameter. If tooth tip is rounded, R and C is considered in contact ratio.

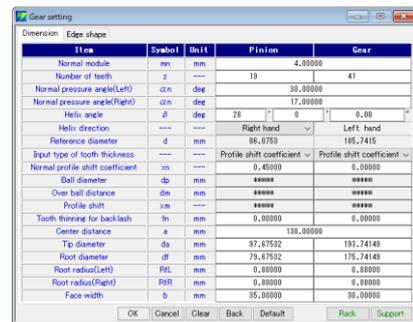
(1) center distance and shift coefficient have the following 3 relationships.

- <1> shift coefficient is given to pinion and gear to determine center distance.
- <2> based on center distance, shift factor of each gear is determined.
- <3> center distance is set, regardless of shift coefficient.

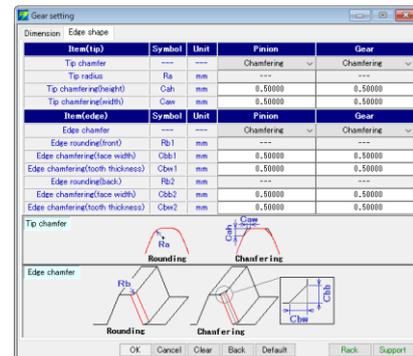
(2) shift coefficient is set per following 4 types;

- <1> directly enter shift coefficient
- <2> based on split tooth thickness, shift coefficient is set
- <3> based on over ball dimension, shift coefficient is set
- <4> addendum modification, shift coefficient is set

For inputting dislocation coefficients, in addition to the direct input method of dislocation coefficients, the dislocation coefficients can also be inversely calculated based on the tooth thickness. Since it is not possible to measure the "tangential tooth thickness" of the asymmetric tooth gear, it is not included in the setting method of the dislocation coefficient. Fig.22.3 shows the specification setting screen, and Fig.22.4 to 22.6 shows the dimensional results. Fig.22.7 shows the over ball measurement position map of the asymmetric tooth gear.



(a) gear dimension



(b) chamfering

Fig.22.3 gear specification

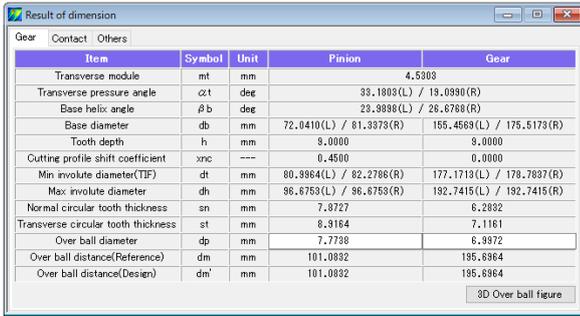


Fig.22.4 dimension result-1

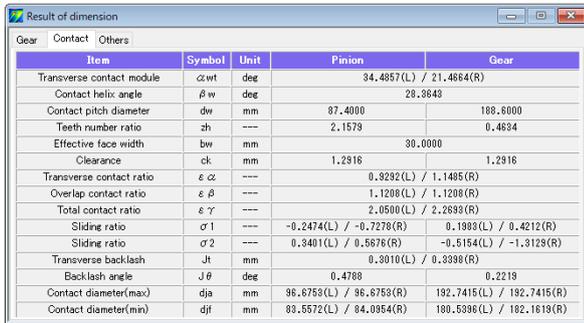


Fig.22.5 dimension result-2

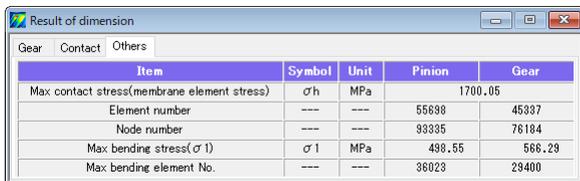
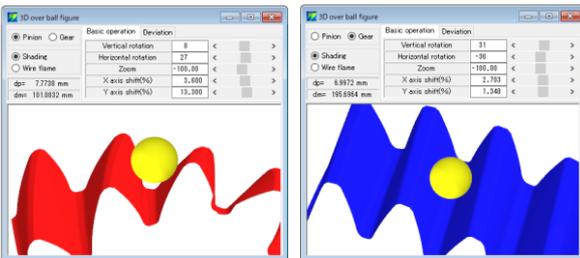


Fig.22.6 dimension result-3



(a) pinion (b) gear

Fig.22.7 over ball diameter

25.5 Tooth profile

Meshing drawing is shown in Fig.22.8. As shown in support form, zoom, distance measurement, R-measurement, diameter, involute modification, line of action, display and rotation function are available.

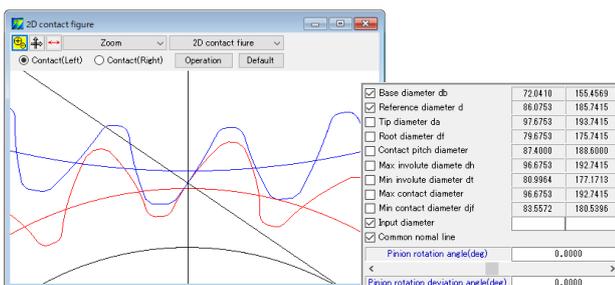


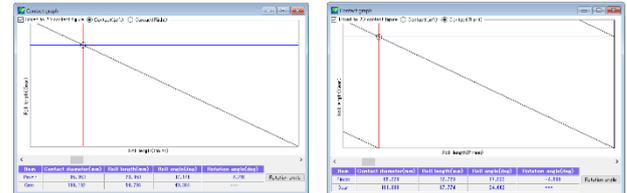
Fig.22.8 meshing drawing & support form

22.6 Contact line and sliding ratio graph

The contact line graph is shown in Fig.22.9. This graph shows the

relation of the meshing well because the line of action length of the gear is shown in the vertical axis with the line of action length of the pinion shown in the transverse. In the Fig.22.9, when the contact diameter of the pinion is 85.853 mm, the contact diameter of the gear is 190.192 mm. Also, the line of action length of this pinion is 23.350 mm and the gear is 54.786 mm.

Moreover, the meshing of the tooth can be grasped because are connected with contact profile (Fig.22.8). The rotation angle computation (Fig.22.10) is the auxiliary calculation function to compute relation between the contact diameter, the line of action length and the roll angle and then the rotation angle. And, the sliding ratio graph is shown in Fig.22.11.



(a) left flank (b) right flank

Fig.22.9 contact line

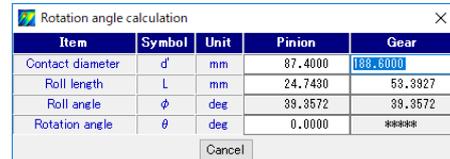
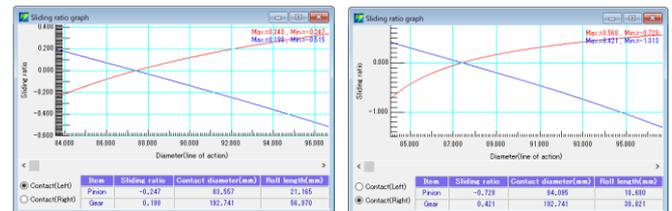


Fig.22.10 rotation angle (left flank)



(a) left flank (b) right flank

Fig.22.11 sliding ratio

22.7 Tooth surface element setting

The tooth surface element setting is shown in Fig.22.12. It sets a torque, and Young's modulus, Poisson's ratio and then the tooth profile distribution number and a pitch error with this screen. The plastic gear can be analyzed by setting Young's modulus and Poisson's ratio. The analysis tooth profile can choose 1 tooth, 3 teeth, 5 teeth. It chooses 5 teeth when total contact ratio is big.

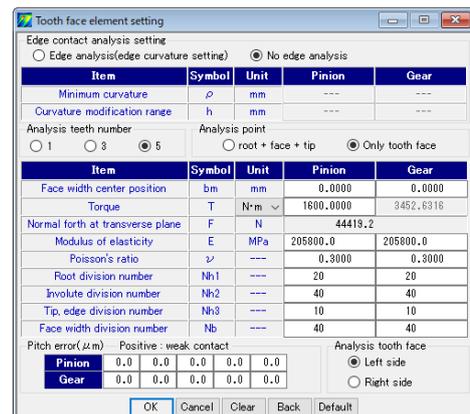


Fig.22.12 tooth surface element setting (left flank)

22.8 The profile and lead modification setting

There are a profile and lead modification and three kinds (Type1-3) of the fixed form respectively. In this example, it gives the pinion a profile modification (Fig.22.13, 22.14) but a gear isn't modification. Incidentally, in this example, the gear is not modification.

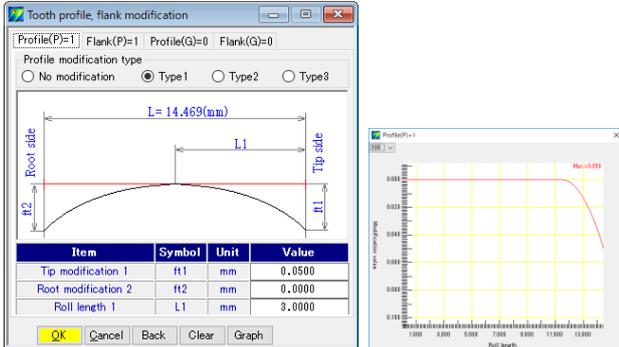


Fig.22.13 tooth modification and graph (×100)

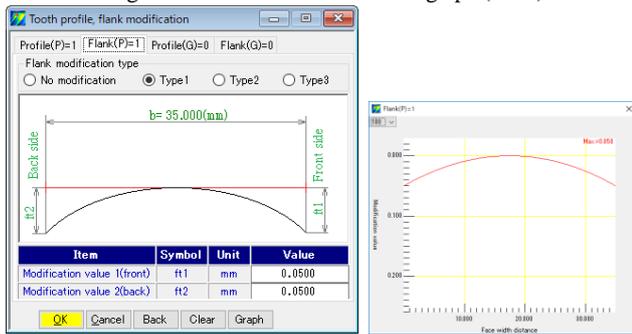
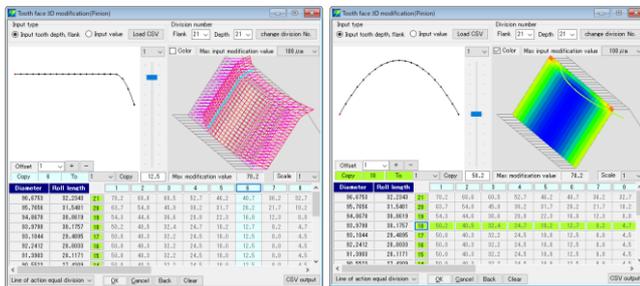


Fig.22.14 lead modification and graph (×100)

22.9 Tooth modification (3D) setting

Like Fig.22.15, the tooth surface modification (3D) can type in directly. Also, the profile modification which was set at Fig.22.13 and Fig.22.14 can be taken over, too. As for Fig.22.15, it is displaying the modification which was set at Fig.22.13 and Fig.22.14 by 3D-profile (gear is a theory tooth profile.). This tooth profile can be output by the [CSV] file. Also, this screen can read the inspection data (csv).

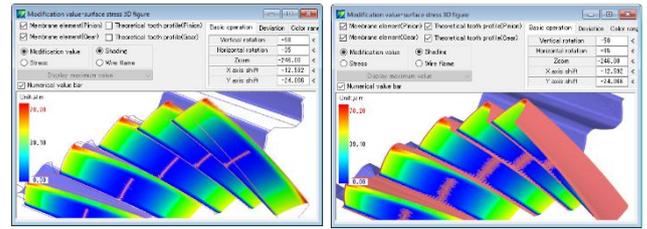


(a) profile modification (b) color palette distribution

Fig.22.15 profile modification (Ex. pinion)

22.10 Profile modification & tooth surface stress (3D)

The tooth profile which was set with the Fig.22.15 can be confirmed with 3D figure. The gear can be turned by the support form and it is possible to make it magnify a gear figure. Moreover, the contact pattern by the tooth when giving an error can be confirmed. Fig.22.16(a) is a modified tooth profile and (b) is the adjusted figure which piled a theory tooth profile on it. Also, a tooth surface element mesh model is shown to Fig.22.17.



(a) tooth modification (b) tooth modification + profile

Fig.22.16 tooth surface element

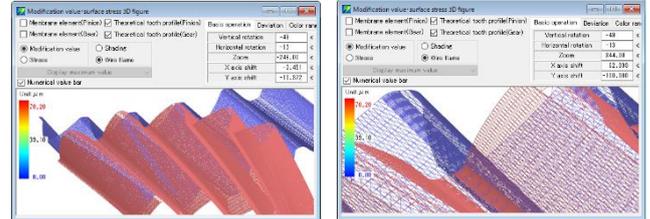


Fig.22.17 tooth surface element model (mesh / Fig.22.12)

22.11 Tooth surface stress analysis condition setting

The gear specification and torque and then, it analyzes the tooth surface stress when giving a tooth surface modification. There are two 1 angle pitch and maximum contact angle kinds of setting of an analysis angle range (Free angle can be set). It sets start angle $\theta_s = -28.578^\circ$ and end angle $\theta_e = 36.102^\circ$ like Fig.22.18 as the computation and divide that contact angle into 60. Then calculate by giving discrepancy error $\phi_1 = 0.01^\circ$ and parallelism error $\phi_2 = -0.001^\circ$. This axis angle error is the error angle when the bearing or the gear box is distorted by the load, which causes a change in the tooth contact and a change in the stress distribution.

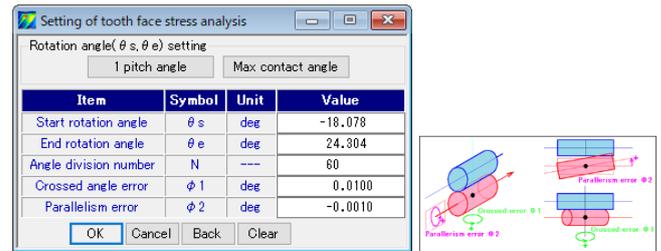
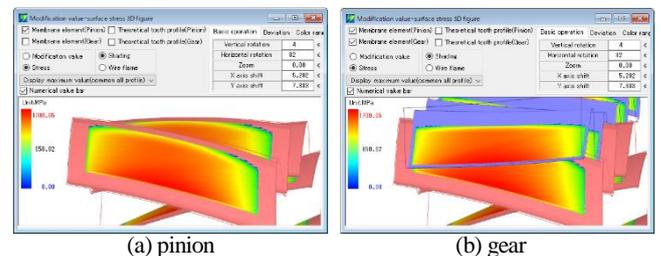


Fig.22.18 tooth surface analysis setting screen, ϕ_1 and ϕ_2

22.12 Tooth surface stress analysis result (3D diagram)

The results of the tooth surface stress analysis are shown in Fig.22.19. In addition, the stress distribution with narrowed stress range is shown in Fig.22.20. In this way, by narrowly displaying the stress range, the range where large stress is generated is well understood. Also, as shown in Figure 22.21, the rotation angle of the pinion with the maximum stress ($\sigma_{Hmax} = 1700$ MPa) is $\theta_p = -3.711^\circ$ and the minimum stress ($\sigma_{Hmin} = 1498$ MPa) is $\theta_p = 7.064^\circ$.



(a) pinion (b) gear

Fig.22.19 tooth surface stress ($\sigma_{Hmax} = 1700$ MPa)

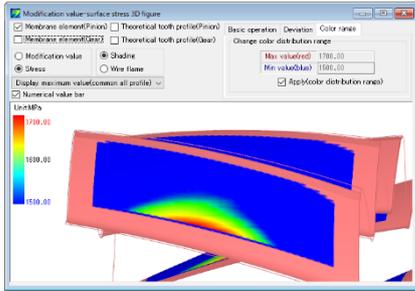
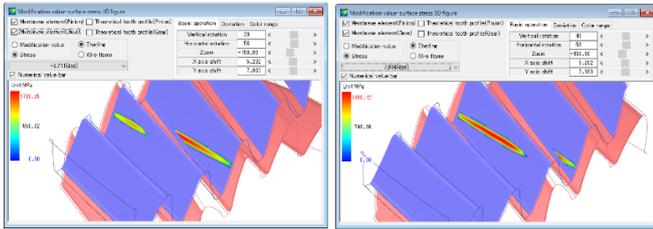


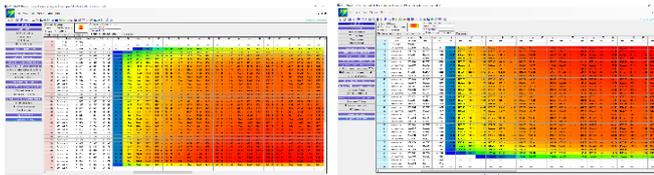
Fig.22.20 tooth surface stress (area: $\sigma_H=1.5\sim 1.7\text{GPa}$)



(a) $\sigma_{Hmax}=1700\text{MPa}(\theta_p=3.711^\circ)$ (b) $\sigma_{Hmin}=1498\text{MPa}(\theta_p=7.064^\circ)$

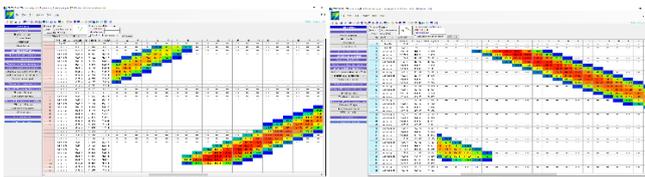
Fig.22.21 tooth surface stress (max. and min.)

The stress distribution (cell display) of the entire tooth surface is shown in Fig.22.22. In the case of example, we display the stress in the area of 98 in the tooth width direction (including the tooth width chamfer) and 70 in the tooth direction (including the tooth tip chamfer) so the stress value at the tooth surface position is understood. In addition, the stress value displayed here can be output as a CSV file. Stress at each rotation angle can display stress distribution corresponding to pinion rotation angle continuously as shown in Fig. 22.23, so it is possible to grasp stress change and contact position.



(a) pinion (b) gear

Fig.22.22 tooth surface stress, cell ($\sigma_{Hmax}=1700\text{MPa}$)



(a) pinion (b) gear

Fig.22.23 tooth surface stress on $\theta_p=3.711^\circ$ ($\sigma_{Hmax}=1700\text{MPa}$)

22.13 Flash temperature, friction coefficient, oil film thickness etc.

Fig.22.24 shows the setting screen for flash temperature calculation. Here, material (thermal conductivity) is selected in addition to the rotation speed and tooth surface roughness (Fig. 22.25). Mineral oils and synthetic oils can be selected for the type of lubricant, but in case of nonstandard, kinematic viscosity and average temperature of oil can be arbitrarily set. Calculation results of flash temperature, coefficient of friction, oil film thickness are shown in Fig.22.26 to 22.33. The probability of occurrence of scuffing and probability of wear are shown in Fig.22.34.

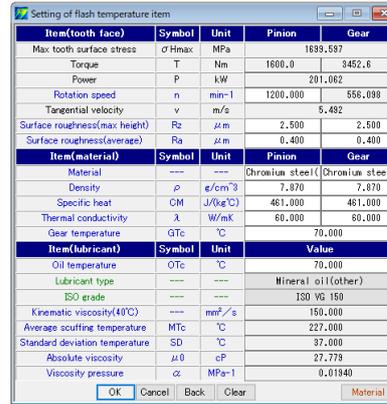


Fig.22.24 flash temperature setting

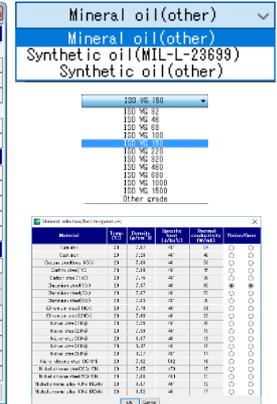
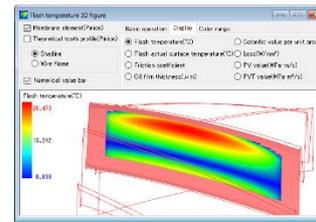
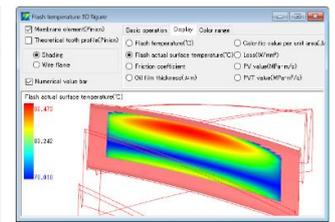


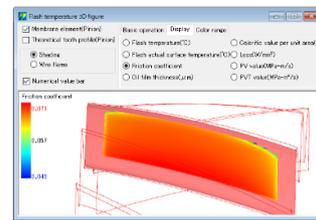
Fig.22.25 material and oil



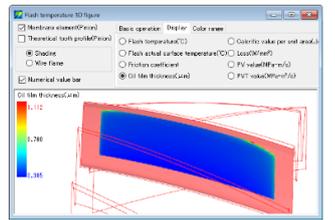
$T_{fF}=26.5(^\circ\text{C})$
Fig.22.26 flash temperature



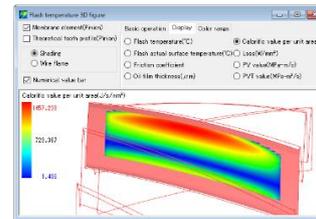
$T_{fB}=96.5(^\circ\text{C})$
Fig.22.27 gear temperature



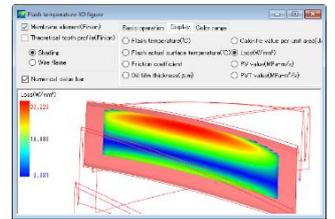
$\mu_{max}=0.071$
Fig.22.28 friction coefficient



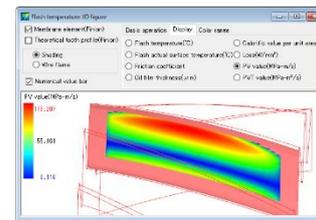
$\lambda_{min}=0.305(\mu\text{m})$
Fig.22.29 oil film thickness



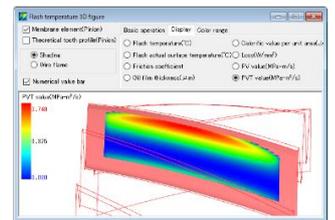
$J_{max}=1457(\text{J/s/mm}^2)$
Fig.22.30 calorific value



$W_{max}=33.2(\text{W})$
Fig.22.31 power loss



$PV_{max}=110.2(\text{MPa}\cdot\text{m/s})$
Fig.22.32 PV value



$PVT_{max}=0.749(\text{MPa}\cdot\text{m}^2/\text{s})$
Fig.22.33 PVT value

Damage probability · loss			
Item	Symbol	Unit	Value
Probability of scuffing occurrence	η_s	%	<5
Probability of abrasion occurrence	η_f	%	5.00
Power loss	η_e	%	0.77

Fig.22.34 damage probability

22.14 Edge analysis (option)

In paragraphs 22.11 to 22.14, we analyzed the involute tooth surface, but here we show the result of the end analysis of the tooth tip and side part (Fig.22.35, end set at R = 1.0 mm).

As a result of analysis, as shown in Fig.22.36, large stress $\sigma_{Hmax}=4423$ MPa is generated in pinion tooth and gear tooth tip. In the analysis of the involute tooth surface, the flash temperature is 26.5 °C at the tooth tip as shown in Fig.22.26. However, in the edge analysis, it can be seen that as shown in Fig.22.37, the pinion tooth rose greatly to 105 °C.

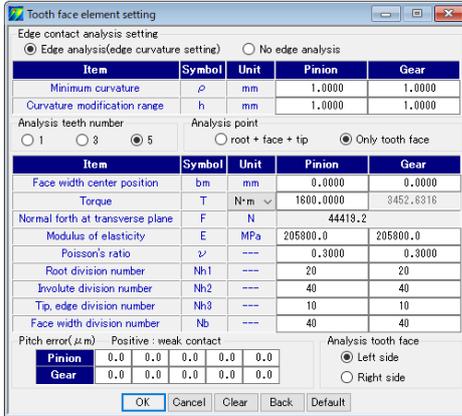
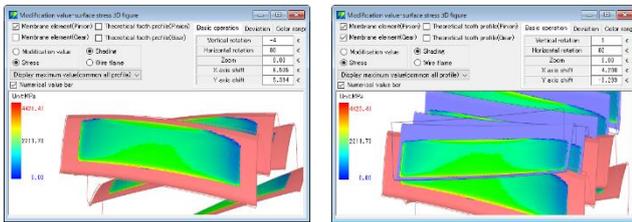
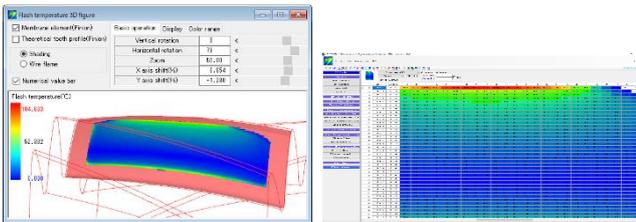


Fig.22.35 tooth surface element setting (edge analysis)



(a) pinion (b) gear

Fig.22.36 tooth surface stress (edge analysis, $\sigma_{Hmax}=4423$ MPa)



(a) tooth profile (b) cell

Fig.22.37 flash temperature, $T_f=105(^{\circ}C)$

22.15 FEM analysis

In the analysis condition of Fig.22.12, to make FEM analysis, create a mesh model in Fig.22.38. Here we create a mesh with the standard model, but there are two ways of setting, one is to determine the tooth profile with accuracy and the other is to determine the tooth profile by the number of divisions.

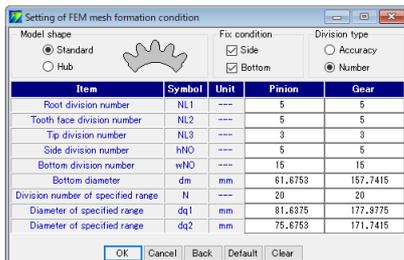
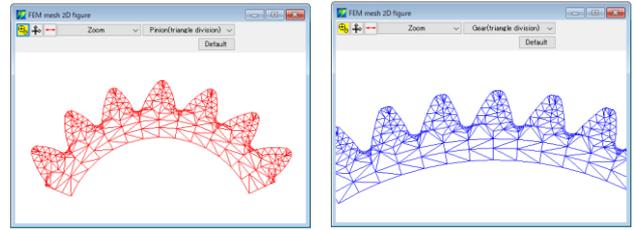


Fig.22.38 mesh model setting

The meshed teeth can be confirmed with the 2D mesh model as shown in Fig.22.39 or the 3D mesh model in Fig.22.40. Also, 3D-FEM mesh elements can display coordinates and nodes as shown in Fig.22.41.



(a) pinion (b) gear

Fig.22.39 2D-mesh model

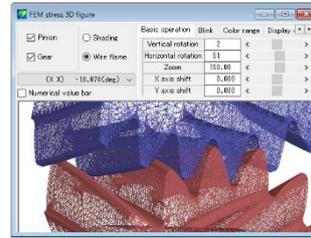


Fig.22.40 3D-mesh model

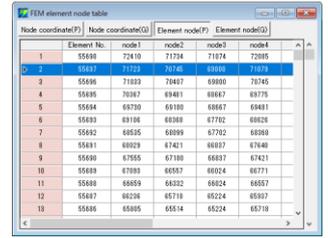


Fig.22.41 element nod table

The mesh model can be generated as a rim / hub model as shown in Fig.22.42, so it is effective for gears with low elastic modulus like plastic gears.

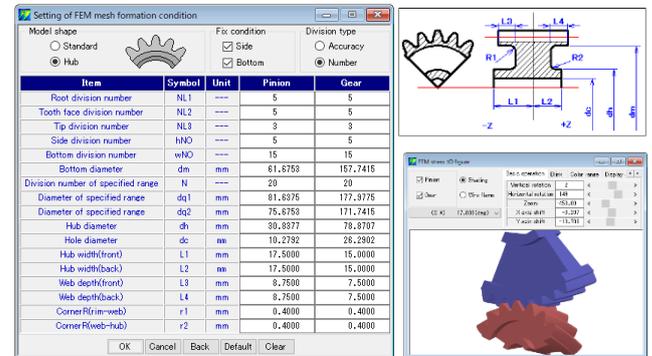


Fig.22.42 rim / hub model

Next, an example of FEM analysis using the mesh model set in Fig.22.38 is explained below. Since the angle (-28.578 ° to 36.102 °) set in the tooth surface analysis setting in Fig.22.18 is divided into 60, the angle of $\theta_p = 14.247$ ° (Fig.22.21) with the largest tooth surface stress is selected and subjected to FEM analysis. If you want to know the change in the bending stress within the meshing angle, check the in Fig. 22.43 to calculate 60 pairs of bending stress. Since the number of analyzes is large, it is effective to select only the required meshing angle and calculate. The items to be analyzed are the stress, displacement and strain shown in Fig.22.44. FEM analysis results are shown in Fig.22.45 ~ 22.48.

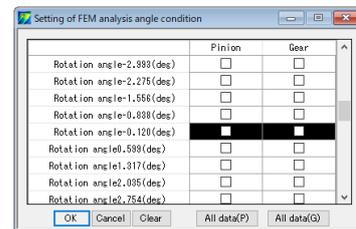


Fig.22.43 FEM analysis choice

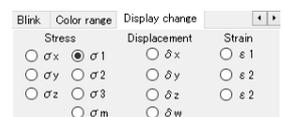
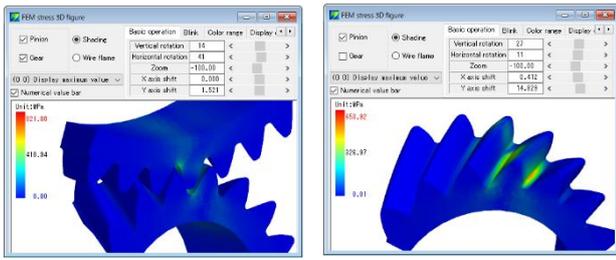
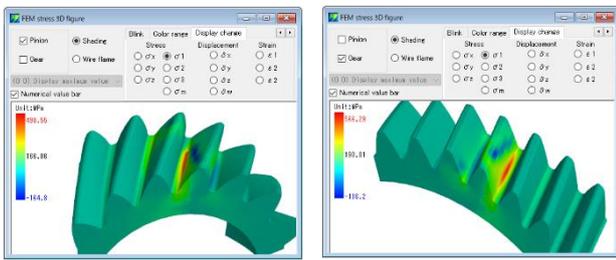


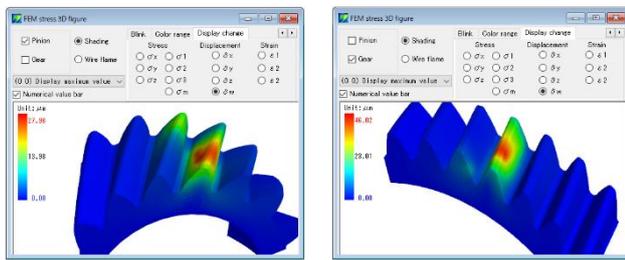
Fig.22.44 kind of the analysis



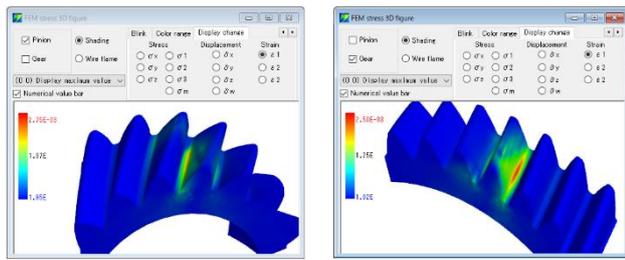
(a) one pair gear
 (b) pinion, $\sigma_{mmax}=654\text{MPa}$
 Fig.22.45 σ_m (Mises stress), $\theta_p=-0.120^\circ$



(a) pinion, $\sigma_{1max}=499\text{MPa}$
 (b) gear, $\sigma_{1max}=566\text{MPa}$
 Fig.22.46 maximum principal stress



(a) pinion, $\delta_{max}=28.0\mu\text{m}$
 (b) gear, $\delta_{max}=46.0\mu\text{m}$
 Fig.22.47 displacement



(a) pinion, $\epsilon_{1max}=2.75 \times 10^{-3}$
 (b) gear, $\epsilon_{1max}=2.50 \times 10^{-3}$
 Fig.22.48 distortion

In the analysis result table of Fig.22.49, it is understood that the element number of the maximum value $\sigma_{1max}=499\text{MPa}$ of the maximum principal stress of the pinion is 336023. If you enter this number in "Blink" in Fig.22.50, it can be confirmed in the stress distribution chart (▲:flashes). After the FEM analysis result, as shown in Fig.22.51, stress at any position in the tooth width direction can be displayed. Fig.22.51 shows the stress at the tooth width center position ($z_d=-3\text{mm}$).

Element No.	σ_x	σ_y	σ_z	σ_{1max}	σ_{2max}	σ_{3max}	Max. strain
1	336023	202.89	202.84	70.88	229.67	-72.25	-4.18
2	336023	202.70	202.70	69.80	229.64	-72.25	-4.75
3	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
4	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
5	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
6	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
7	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
8	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
9	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
10	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
11	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
12	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
13	336023	202.71	202.71	69.80	229.64	-72.25	-4.75
14	336023	202.71	202.71	69.80	229.64	-72.25	-4.75

Fig.22.49 analysis result list

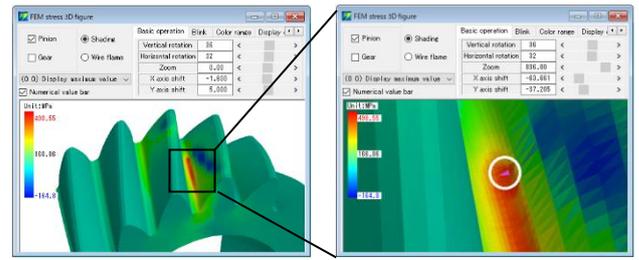
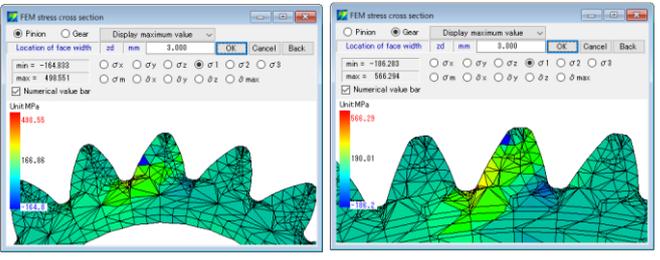


Fig.22.50 pinion, σ_{1max} point, $\sigma_{1max}=499\text{MPa}$



(a) pinion, $\sigma_{1max}=499\text{MPa}$
 (b) gear, $\sigma_{1max}=566\text{MPa}$
 Fig.22.51 FEM-section ($z_d=3\text{mm}$)

22.16 Lifetime

Calculate lifetime after tooth surface stress analysis and FEM analysis. Fig.45.52 shows the lifetime when the allowable stress value for material's tooth surface strength is $\sigma_{Hlim}=2000\text{MPa}$ and the allowable stress value for bending strength is $\sigma_{Flim}=400\text{MPa}$.

Item	Symbol	Unit	Pinion	Gear
Max contact stress	σ_{Hmax}	MPa	1839.587	1700.049
Max bending stress (σ_1)	σ_1	MPa	498.551	566.294
Rotation speed	n	min ⁻¹	1200.000	566.038
Allowable Hertzian stress	σ_{Hlim}	MPa	2000.000	2000.000
Allowable bending stress	σ_{Flim}	MPa	400.000	400.000
Overload cycles	---	---	1	---
Nitride material	---	---	No nitride material	---
Working condition	---	---	Normal	---
Item(Contact)	Symbol	Unit	Pinion	Gear
Expected stress repeat factor	ZN	---	0.950	0.950
Expected lifespan load number	Nc	---	1.00E+10	1.00E+10
Expected lifespan	Lc	hrs	3.09E+05	3.09E+05
Item(bendme)	Symbol	Unit	Pinion	Gear
Expected stress repeat factor	ZN	---	1.248	1.416
Expected lifespan load number	Nc	---	6.56E+05	2.25E+05
Expected lifespan	Lc	hrs	9.10E+00	6.74E+00

Fig.22.52 lifetime

22.17 Transmission error (option)

Fig.22.53 and Fig.22.54 show the rotation transmission errors and Fourier analysis results within the rotation angle given on the tooth surface analysis setting screen in Fig.22.18.

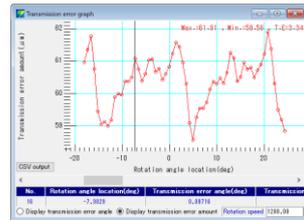


Fig.22.53 transmission error

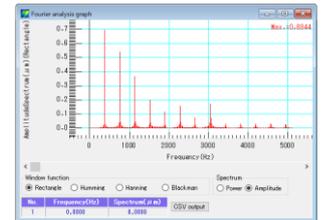


Fig.22.54 Fourier analyses

22.18 Analysis of optimal tooth surface modification (option)

Optimal modification value analysis

As shown in Fig.22.14, when considering the torque and the shaft angle error instead of uniformly determining the tooth surface modification, it is a function that can determine the amount of correction that minimizes the tooth surface stress.

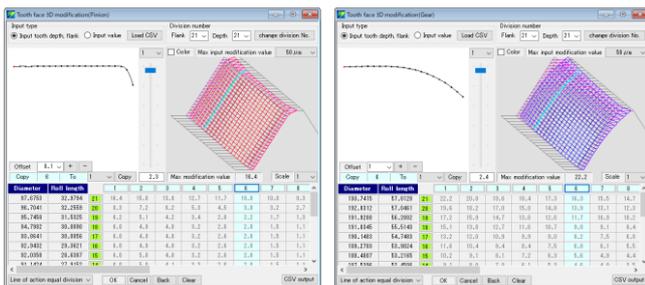
As an example, Fig.22.55 and Fig.22.56 show the optimal tooth

surface modification calculated using the torque in Fig. 22.3 and the axis angle error in Fig. 22.18 with the gear.

Item	Symbol	Unit	Value
Crossed angle error	$\phi 1$	deg	0.0100
End face deviation(0.5 b sin $\phi 1$)	Δv	mm	0.0031
Parallelism error	$\phi 2$	deg	-0.0010
Tip interference amount(0.5 da sin $\phi 2$)	Δu	mm	-0.0009
1 pitch angle division number	N	---	10

Item	Symbol	Unit	Pinion	Gear
Frequency of iterative calculation	N	---	---	5
Modification distribution ratio	γ	---	0.5000	0.5000
Modification value(lower)	f _{ts}	mm	0.0001	0.0001
Modification value(left)	f _{tw}	mm	0.0080	0.0080
Modification value(right)	f _{te}	mm	0.0053	0.0053
Modification value(upper)	f _{tn}	mm	0.0083	0.0117
Modification ratio(lower)	H _{ts}	---	0.8000	0.2564
Modification ratio(left)	H _{tw}	---	0.7429	0.7833
Modification ratio(right)	H _{te}	---	0.1571	0.1000
Modification ratio(upper)	H _{tn}	---	0.1000	0.6609
Modification curve type	Cu	---	Standard	---

Fig.22.55 modification setting



(a) pinion (b) gear
Fig.22.56 optimal tooth surface modification

Next, Fig.22.57 of the tooth surface stress analyzed with the tooth profile of Fig.22.56 is 28% lower than $\sigma_{Hmax}=1700$ MPa in Fig.22.19. Fig. 22.58 shows the flash temperature and Fig.22.59 shows the friction coefficient distribution.

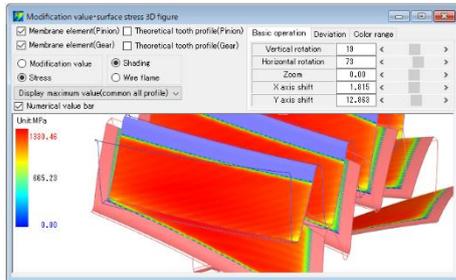
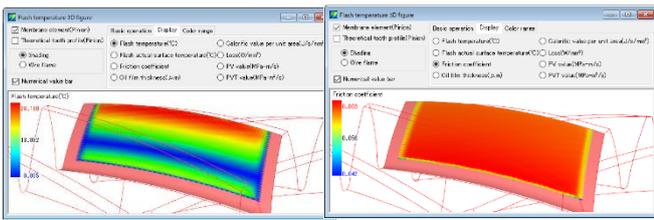


Fig.22.57 tooth surface stress ($\sigma_{Hmax}=1330$ MPa)



$T_n=26.2(^{\circ}C)$ $\mu_{max}=0.069$
Fig.22.58 flash temperature Fig.22.59 friction coefficient

22.19 Analysis of the internal-gear (option)

The analysis result of "external gear \times internal gear" is shown Fig.22.60 to 22.77

Item	Symbol	Left	Right
Pressure angle	α_n	30.0000	17.0000
Addendum factor	ha0	1.0000	1.0000
Dedendum factor	hf0	1.2500	1.2500
Root radius factor(Left)	roL	0.2200	0.2200
Root radius factor(Right)	roR	0.2200	0.2200
Clearance factor	ck0	0.2500	0.2500

Fig.22.60 basic rack

Item	Symbol	Unit	Pinion	Gear
Normal module	m	mm	4.0000	---
Number of teeth	z	---	19	55
Normal pressure angle(Left)	α_n	deg	30.0000	---
Normal pressure angle(Right)	α_n	deg	---	17.0000
Helix angle	β	deg	28	0
Helix direction	---	---	Right hand	Right hand
Reference diameter	d	mm	86.0753	245.1654
Input type of tooth thickness	---	---	Profile shift coefficient	Profile shift coefficient
Normal profile shift coefficient	x_n	---	0.45000	0.30000
Ball diameter	d_b	mm	88.8888	88.8888
Over ball distance	d_m	mm	88.8888	88.8888
Profile shift	x_m	---	88.8888	88.8888
Tooth thinning for backlash	f _n	mm	0.00000	0.00000
Center distance	a	mm	---	80.50000
Tip diameter	d_a	mm	97.67532	249.56541
Root diameter	d_f	mm	79.67532	261.56541
Root radius(Left)	R _L	mm	0.88000	0.88000
Root radius(Right)	R _R	mm	0.88000	0.88000
Face width	b	mm	35.00000	30.00000

Fig.22.61 gear specification

Item	Symbol	Unit	Pinion	Gear
Transverse module	m_t	mm	---	4.5393
Transverse pressure angle	α_t	deg	---	30.1693(L) / 18.8398(R)
Base helix angle	β_b	deg	---	29.8936(L) / 18.6769(R)
Base diameter	d_b	mm	72.0410(L) / 81.3973(R)	209.5397(L) / 235.4500(R)
Tooth depth	h	mm	5.0000	8.0000
Cutting profile shift coefficient	x_{nc}	---	0.4500	0.3000
Min involute diameter(TIP)	d_t	mm	80.3984(L) / 82.2788(R)	244.5654(L) / 244.5654(R)
Max involute diameter	d_h	mm	86.6763(L) / 86.6763(R)	280.8888(L) / 280.8888(R)
Normal circular tooth thickness	s_n	mm	7.8727	6.2285
Transverse circular tooth thickness	s_t	mm	6.9184	5.9180
Over ball diameter	d_m	mm	7.0000	7.0000
Over ball distance(Reference)	d_m	mm	88.7896	241.2462
Over ball distance(Design)	d_m'	mm	88.7896	241.2462

Fig.22.62 dimension result-1

Item	Symbol	Unit	Pinion	Gear
Transverse contact module	α_{wt}	deg	82.0248(L) / 18.8189(R)	---
Contact helix angle	β_m	deg	---	27.8948
Contact pitch diameter	d_w	mm	84.9722	245.3722
Teeth number ratio	z_h	---	2.8947	0.3455
Effective face width	b_w	mm	---	30.0000
Clearance	ck	mm	1.4450	1.4450
Transverse contact ratio	ϵ_{α}	---	0.8268(L) / 1.2154(R)	---
Overlap contact ratio	ϵ_{β}	---	1.1208(L) / 1.1208(R)	---
Total contact ratio	ϵ_{γ}	---	2.0477(L) / 2.3362(R)	---
Slide ratio	σ_H	---	-0.0415(L) / +0.1892(R)	0.0958(L) / 0.1439(R)
Slide ratio	σ_F	---	0.1971(L) / 0.2468(R)	-0.2464(L) / -0.5304(R)
Transverse backlash	J_t	mm	---	0.3467(L) / 0.3915(R)
Backlash angle	J_{θ}	deg	0.5515	0.1905
Contact diameter(max)	d_a	mm	86.6763(L) / 86.6763(R)	256.7924(L) / 255.3544(R)
Contact diameter(min)	d_f	mm	83.8886(L) / 83.8886(R)	244.5654(L) / 244.5654(R)
Involute interference	---	---	No occur(Left)/No occur(right)	---
Trimming	---	---	No occur(Left)/No occur(right)	---
Trochoid interference	---	---	No occur(Left)/No occur(right)	---
Filler/roof interference	---	---	No occur(Left)/No occur(right)	---

Fig.22.63 dimension result-2

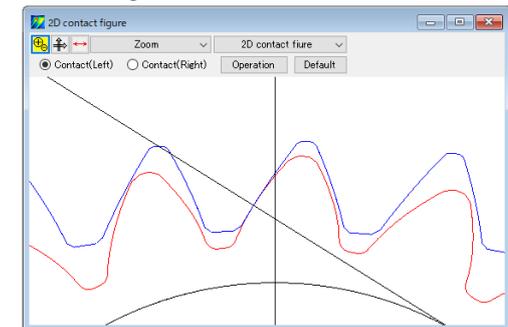
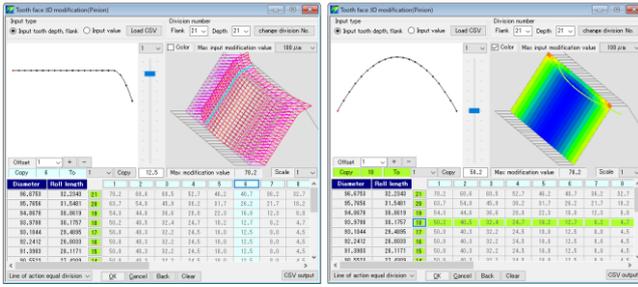


Fig.22.64 meshing drawing



(a) profile modification (b) color palette distribution
Fig.22.65 profile modification (same: Fig.22.15)

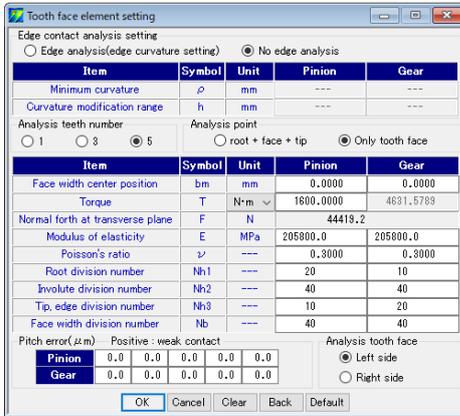


Fig.22.66 tooth surface element setting

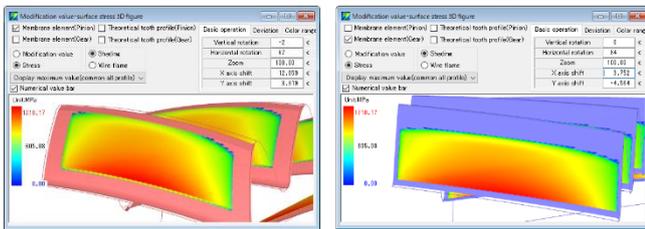


Fig.22.67 tooth surface stress ($\sigma_{Hmax}=1210MPa$)

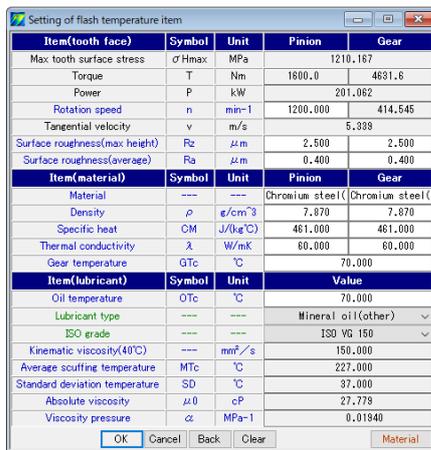
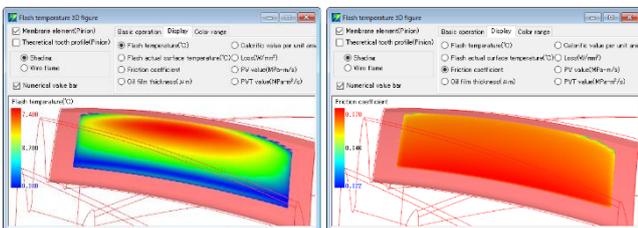


Fig.22.68 flash temperature setting



$T_f=7.40(°C)$ $\mu_{max}=0.070$
Fig.22.69 flash temperature Fig.22.70 friction coefficient

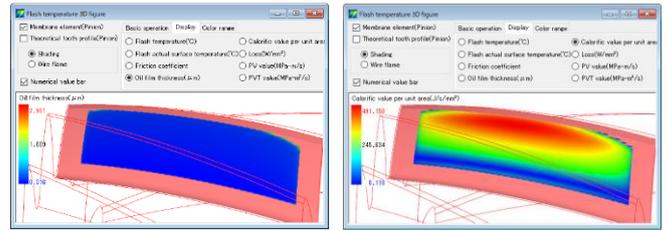


Fig.22.71 oil film thickness Fig.22.72 calorific value

Item	Symbol	Unit	Value
Probability of scuffing occurrence	η_s	%	<5
Probability of abrasion occurrence	η_f	%	5.00
Power loss	η_e	%	0.46

Fig.22.73 damage probability

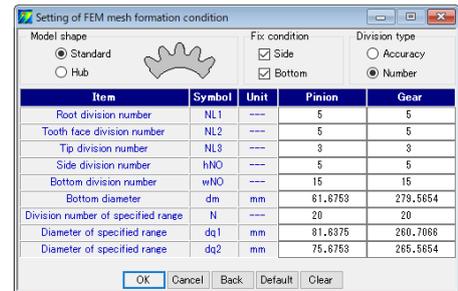
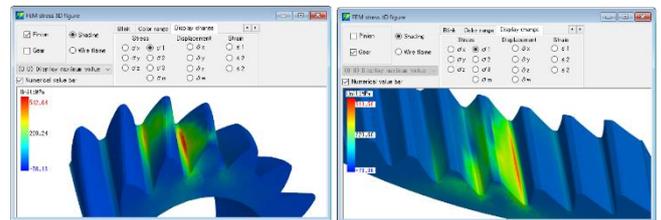
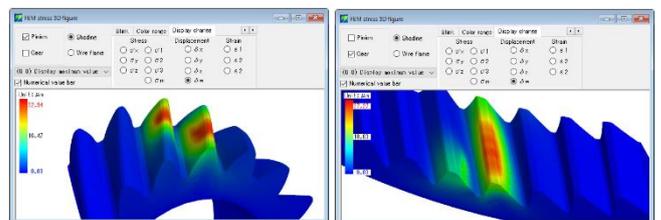


Fig.22.74 mesh model setting



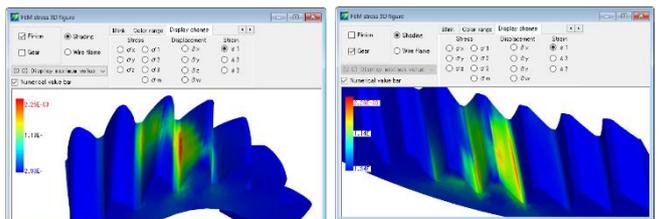
(a) pinion, $\sigma_{1max}=513MPa$ (b) gear, $\sigma_{1max}=520MPa$

Fig.22.75 maximum principal stress



(a) pinion, $\delta_{max}=32.9\mu m$ (b) gear, $\delta_{max}=37.3\mu m$

Fig.22.76 displacement



(a) pinion, $\epsilon_{1max}=2.25 \times 10^{-3}$ (b) gear, $\epsilon_{1max}=2.28 \times 10^{-3}$

Fig.22.77 distortion